## Communications in Nonlinear Analysis

# Classification of positive solutions for nonlinear differential systems 

Lianwen Wang ${ }^{\text {a,* }}$<br>${ }^{a}$ School of Computer Science and Mathematics, University of Central Missouri, Warrensburg, MO 64093, USA


#### Abstract

The classification of positive solutions for a class of nonlinear differential systems is investigated. Necessary and sufficient conditions are established for the existence of certain solutions. Sufficient conditions for the nonexistence of certain solutions are also discussed. In particular, some sufficient conditions for the nonexistence are optimal in some sense.


Keywords: Classification, existence, nonexistence, positive solution, nonlinear differential system. 2010 MSC: 34C11, 34C12

## 1. Introduction

In this paper we consider the classification of positive solutions for the system of first order nonlinear differential equations

$$
\begin{align*}
x^{\prime}(t) & =F(t, y(t))  \tag{1.1}\\
y^{\prime}(t) & =G(t, x(t)),
\end{align*}
$$

where $F, G:[a, \infty) \times \mathbb{R} \rightarrow \mathbb{R}$ are continuous functions. $r F(t, r)>0$ and $r G(t, r)>0$ for all $r \neq 0$ and $t \geq a$. There exist two continuous functions $a(t), b(t):[a, \infty) \rightarrow(0, \infty)$, two continuous and increasing functions $f(r), g(r): \mathbb{R} \rightarrow \mathbb{R}$, and two real numbers $\alpha>1, \beta>1$ such that for $t \geq a$

$$
\begin{align*}
a(t) f(y) \leq F(t, y) & \leq \alpha a(t) f(y), \\
b(t) g(x) \leq G(t, x) & \leq \beta b(t) g(x) . \tag{1.2}
\end{align*}
$$

Remark 1.1. Many nonseparable functions $F$ and $G$ satisfy (1.2); for example, let $F(t, y)=2 t y+\sin (t y)$ where $t \geq 1$. Then $r F(t, r)>0$ for all $r \neq 0$ and $t y \leq F(t, y) \leq 3 t y$.

[^0]A pair of functions $(x(t), y(t))$ is called a solution of system (1.1) with maximal existence interval $\left[a, \alpha_{x y}\right)$, $a<\alpha_{x y} \leq \infty$, if both $x(t)$ and $y(t)$ are differentiable and satisfy system (1.1) on $\left[a, \alpha_{x y}\right)$. A solution $(x(t), y(t))$ is said to be eventually positive if there exists a $b \geq a$ such that both $x(t)$ and $y(t)$ are positive on $\left[b, \alpha_{x y}\right)$. Note that there are some general conditions to guarantee that the solutions can be extended to $[a, \infty)[12]$. We restrict our discussions to solutions of system (1.1) that can be extended to $[a, \infty)$.

Classification, existence, asymptotic behavior, and other properties of solutions of some special cases of system (1.1)-second order nonlinear differential equations-have been studied in details; see $[1,2,4,6,9,10$, 11,13 ] and many other publications. The investigation for nonlinear differential systems can be found in $[3,7,8]$ and other literatures, but all these discussions focus on separable nonlinear differential systems

$$
\begin{align*}
x^{\prime}(t) & =a(t) f(y(t)) \\
y^{\prime}(t) & =b(t) g(x(t)) \tag{1.3}
\end{align*}
$$

In this paper, we discuss the classification of all eventually positive solutions of system (1.1) and provide results of existence and nonexistence of certain solutions. Our results completely extend all the results of [8] to the nonseparable differential system (1.1), and moreover, we establish some nonexistence theorems for certain solutions and show that some sufficient conditions for the nonexistence are optimal in some sense.

The following assumptions are imposed for the discussions:
(H1A) There exists a real number $K>0$ such that

$$
|f(u v)| \leq K|f(u)||f(v)|, \quad \forall u, v \in \mathbb{R}
$$

(H1B) There exists a real number $M>0$ such that

$$
|g(u v)| \leq M|g(u)||g(v)|, \forall u, v \in \mathbb{R}
$$

(H2A) There exists a real number $r_{0}>0$ such that

$$
\int_{ \pm r_{0}}^{ \pm \infty} \frac{d r}{f(g(r))}=\infty
$$

(H2B) There exists a real number $r_{0}>0$ such that

$$
\int_{ \pm r_{0}}^{ \pm \infty} \frac{d r}{g(f(r))}=\infty
$$

Define four classes of solutions of system (1.1) below. We will show that all eventually positive solutions belong to one of the four classes.

$$
\begin{aligned}
S(c, c) & =\left\{(x, y): \lim _{t \rightarrow \infty} x(t)=c_{1}>0, \lim _{t \rightarrow \infty} y(t)=c_{2}>0\right\} \\
S(c, \infty) & =\left\{(x, y): \lim _{t \rightarrow \infty} x(t)=c_{1}>0, \lim _{t \rightarrow \infty} y(t)=\infty\right\} \\
S(\infty, c) & =\left\{(x, y): \lim _{t \rightarrow \infty} x(t)=\infty, \lim _{t \rightarrow \infty} y(t)=c_{2}>0\right\} \\
S(\infty, \infty) & =\left\{(x, y): \lim _{t \rightarrow \infty} x(t)=\infty, \lim _{t \rightarrow \infty} y(t)=\infty\right\} .
\end{aligned}
$$

Let

$$
A=\int_{a}^{\infty} a(t) d t, \quad B=\int_{a}^{\infty} b(t) d t
$$

There are four possible cases for $A$ and $B: A=\infty$ and $B=\infty, A=\infty$ and $B<\infty, A<\infty$ and $B=\infty$, and $A<\infty$ and $B<\infty$. In the following sections we will consider the classification with each of these four cases as in [8].

## 2. The Case $A=\infty$ And $B=\infty$

Theorem 2.1. Suppose that $A=\infty$ and $B=\infty$. Then any eventually positive solutions of (1.1) belong to $S(\infty, \infty)$.

Proof. Let $(x, y)$ be an eventually positive solution of system (1.1). Then $x^{\prime}(t)>0$ and $y^{\prime}(t)>0$ for $t \geq b$. So, $x(t) \geq x(b)$ and $y(t) \geq y(b)$ for $t \geq b$. Therefore, we have

$$
x(t)=x(b)+\int_{b}^{t} F(s, y(s)) d s \geq \int_{b}^{t} a(s) f(y(s)) d s \geq f(y(b)) \int_{b}^{t} a(s) d s
$$

and

$$
y(t)=y(b)+\int_{b}^{t} G(s, x(s)) d s \geq \int_{b}^{t} b(s) g(x(s)) d s \geq g(x(b)) \int_{b}^{t} b(s) d s
$$

This implies that $(x, y) \in S(\infty, \infty)$.
Remark 2.2. Theorem 2.1 extends [8] Theorem 2.1 to nonseparable differential system (1.1).

## 3. The Case $A=\infty$ And $B<\infty$

Theorem 3.1. Suppose that $A=\infty$ and $B<\infty$. Then any eventually positive solutions of (1.1) belong to either $S(\infty, \infty)$ or $S(\infty, c)$.

Proof. Let $(x, y)$ be an eventually positive solution of system (1.1). Then $x^{\prime}(t)>0$ and $y^{\prime}(t)>0$ for $t \geq b$. So, $x(t) \geq x(b)$ and $y(t) \geq y(b)$ for $t \geq b$. Note that

$$
x(t)=x(b)+\int_{b}^{t} F(s, y(s)) d s \geq \int_{b}^{t} a(s) f(y(s)) d s \geq f(y(b)) \int_{b}^{t} a(s) d s
$$

So, $x(t) \rightarrow \infty$ as $t \rightarrow \infty$ and $(x, y) \in S(\infty, \infty)$ or $S(\infty, c)$.
Theorem 3.2. Suppose that $A=\infty$ and $B<\infty$. If $S(\infty, c) \neq \emptyset$, then

$$
\begin{equation*}
\int_{a}^{\infty} b(t) g\left(f(c) \int_{a}^{t} a(s) d s\right) d t<\infty \tag{3.1}
\end{equation*}
$$

for some $c>0$.
Proof. Let $(x, y)$ be an eventually positive solution of system (1.1). Then $x^{\prime}(t)>0$ and $y^{\prime}(t)>0$ for $t \geq b$. So, $x(t) \geq x(b)$ and $y(t) \geq y(b)$ for $t \geq b$. Note that

$$
x(t)=x(b)+\int_{b}^{t} F(s, y(s)) d s \geq \int_{b}^{t} a(s) f(y(s)) d s \geq f(y(b)) \int_{b}^{t} a(s) d s
$$

and

$$
\begin{aligned}
y(t) & =y(b)+\int_{b}^{t} G(s, x(s)) d s \\
& \geq \int_{b}^{t} b(s) g(x(s)) d s \\
& \geq \int_{b}^{t} b(s) g\left(f(y(b)) \int_{b}^{t} a(\xi) d \xi\right) d s
\end{aligned}
$$

Therefore,

$$
\int_{b}^{\infty} b(t) g\left(f(y(b)) \int_{b}^{t} a(s) d s\right) d t<\infty
$$

Theorem 3.3. Suppose that $A=\infty$ and $B<\infty$. If

$$
\begin{equation*}
\int_{a}^{\infty} b(t) g\left(\alpha f(c) \int_{a}^{t} a(s) d s\right) d t<\infty \tag{3.2}
\end{equation*}
$$

for some $c>0$, then $S(\infty, c) \neq \emptyset$.
Proof. Take a large $T>a$ such that

$$
\int_{a}^{\infty} b(t) g\left(\alpha f(c) \int_{a}^{t} a(s) d s\right) d t<\frac{c}{2 \beta}
$$

Let $C B[T, \infty)$ be the Banach space of all bounded and continuous functions defined on $[T, \infty)$ with the supremum norm and let $X$ be a subset of $C B[T, \infty)$ defined as

$$
X=\left\{y \in C B[T, \infty): \frac{c}{2} \leq y(t) \leq c, t \geq T\right\}
$$

Clearly, $X$ is a convex and bounded subset of $C B[T, \infty)$. Define an operator $J: X \rightarrow C B[T, \infty)$ as

$$
(J y)(t)=c-\int_{t}^{\infty} G\left(s, \int_{T}^{s} F(\xi, y(\xi)) d \xi\right) d s, t \geq T
$$

In the following we will show that $J$ maps $X$ into $X$, it is continuous, and $J X$ is precompact.
First of all, $J$ maps $X$ into $X$ because for any $y \in X$

$$
\begin{aligned}
c \geq(J y)(t) & \geq c-\int_{T}^{\infty} G\left(t, \int_{T}^{t} F(\xi, y(\xi)) d \xi\right) d t \\
& \geq c-\beta \int_{T}^{\infty} b(t) g\left(\alpha f(c) \int_{a}^{t} a(s) d s\right) d t \\
& \geq c / 2
\end{aligned}
$$

Let $y_{n}, y \in X$ such that $\left\|y_{n}-y\right\| \rightarrow 0$ as $n \rightarrow \infty$. Since $F$ and $G$ are continuous, for each $s \geq T$, we have

$$
G\left(s, \int_{T}^{s} F\left(\xi, y_{n}(\xi)\right) d \xi\right)-G\left(s, \int_{T}^{s} F(\xi, y(\xi)) d \xi\right) \rightarrow 0, n \rightarrow \infty
$$

Also,

$$
\left|G\left(s, \int_{T}^{s} F\left(\xi, y_{n}(\xi)\right) d \xi\right)-G\left(s, \int_{T}^{s} F(\xi, y(\xi)) d \xi\right)\right| \leq 2 \beta b(s) g\left(\alpha f(c) \int_{T}^{s} a(\xi) d \xi\right)
$$

By the Lebesgue's Dominated Convergence Theorem, we have

$$
\begin{aligned}
\lim _{n \rightarrow \infty}\left\|J y_{n}-J y\right\| & =\lim _{n \rightarrow \infty} \sup _{t \geq T} \mid\left(J y_{n}\right)(t)-(J y)(t) \| \\
& \leq \lim _{n \rightarrow \infty} \int_{T}^{\infty}\left|G\left(t, \int_{T}^{t} F\left(s, y_{n}(s)\right) d s\right)-G\left(t, \int_{T}^{t} F(s, y(s)) d s\right)\right| d t \\
& =0
\end{aligned}
$$

Thus, $J$ is continuous.
$J X$ is equicontinuous because for any $t_{1}, t_{2} \geq T$ and $t_{2}>t_{1}$

$$
\begin{aligned}
\left|(J y)\left(t_{2}\right)-(J y)\left(t_{1}\right)\right| & =\int_{t_{1}}^{t_{2}} G\left(t, \int_{T}^{t} F(s, y(s)) d s\right) d t \\
& \leq \beta \int_{t_{1}}^{t_{2}} b(t) g\left(\alpha f(c) \int_{T}^{t} a(s) d s\right) d t
\end{aligned}
$$

Also $J X$ is uniformly bounded. The precompactness of $J X$ follows from Arzelà-Ascoli Theorem.
By Schauder's fixed-point theorem, $J$ has a fixed point in $X$, let it be $\bar{y}$. Define

$$
\bar{x}=\int_{T}^{t} F(s, \bar{y}(s)) d s
$$

It is easy to check that $(\bar{x}, \bar{y})$ is a class $S(\infty, c)$ solution of system (1.1).

Combining Theorem 3.2 and Theorem 3.3, we have
Corollary 3.4. Suppose that $A=\infty$ and $B<\infty$. Then $S(\infty, c) \neq \emptyset$ for system (1.3) if and only if

$$
\int_{a}^{\infty} b(t) g\left(f(c) \int_{a}^{t} a(s) d s\right) d t<\infty
$$

for some $c>0$.
Corollary 3.5. Suppose that $A=\infty, B<\infty$, and (H1B) hold. Then $S(\infty, c) \neq \emptyset$ for system (1.1) if and only if

$$
\begin{equation*}
\int_{a}^{\infty} b(t) g\left(\int_{a}^{t} a(s) d s\right) d t<\infty \tag{3.3}
\end{equation*}
$$

Proof. We will show that (3.1), (3.2), and (3.3) are equivalent under assumption (H1B). Indeed, if (3.2) is satisfied, then (3.1) is satisfied since

$$
\int_{a}^{\infty} b(t) g\left(f(c) \int_{a}^{t} a(s) d s\right) d t \leq \int_{a}^{\infty} b(t) g\left(\alpha f(c) \int_{a}^{t} a(s) d s\right) d t
$$

If (3.1) is true, so is (3.3) because

$$
\begin{aligned}
& \int_{a}^{\infty} b(t) g\left(\int_{a}^{t} a(s) d s\right) d t \\
& =\int_{a}^{\infty} b(t) g\left(\frac{1}{f(c)} f(c) \int_{a}^{t} a(s) d s\right) d t \\
& \leq M g\left(\frac{1}{f(c)}\right) \int_{a}^{\infty} b(t) g\left(f(c) \int_{a}^{t}(s) d s\right) d t
\end{aligned}
$$

If (3.3) holds, so does (3.2) since

$$
\int_{a}^{\infty} b(t) g\left(\alpha f(c) \int_{a}^{t} a(s) d s\right) d t \leq M g(\alpha f(c)) \int_{a}^{\infty} b(t) g\left(\int_{a}^{t} a(s) d s\right) d t
$$

The next result provides the condition for the emptiness of class $S(\infty, \infty)$.
Theorem 3.6. Suppose that $A=\infty, B<\infty$, (H1A), and (H2A) are satisfied. In addition, let (3.3) hold. Then $S(\infty, \infty)=\emptyset$.

Proof. Let $(x, y)$ be an eventually positive solution of system (1.1) that belongs to class $S(\infty, \infty)$. Then $x^{\prime}(t)>0$ and $y^{\prime}(t)>0$ for $t \geq b$. Note that

$$
\begin{aligned}
y(t) & =y(b)+\int_{b}^{t} G(s, x(s)) d s \\
& \leq y(b)+\beta \int_{b}^{t} b(s) g(x(s)) d s \\
& \leq y(b)+\beta g(x(t)) \int_{b}^{t} b(s) d s \\
& =g(x(t))\left(\frac{y(b)}{g(x(t))}+\beta \int_{b}^{t} b(s) d s\right) \\
& \leq g(x(t))\left(\frac{y(b)}{g(x(b))}+\beta \int_{b}^{t} b(s) d s\right) .
\end{aligned}
$$

Choose $L>1$ such that

$$
\frac{y(b)}{g(x(b))}+\beta \int_{b}^{t} b(s) d s \leq L \int_{b}^{t} b(s) d s
$$

we have

$$
y(t) \leq L g(x(t)) \int_{b}^{t} b(s) d s
$$

Applying (H1A) we have

$$
\begin{aligned}
x^{\prime}(t) & =F(t, y(t)) \leq \alpha a(t) f(L g(x(t)) \\
& \leq \alpha K^{2} f(L) a(t) f(g(x(t))) f\left(\int_{b}^{t} b(s) d s\right)
\end{aligned}
$$

Then

$$
\frac{x^{\prime}(t)}{f(g(x(t)))} \leq \alpha K^{2} f(L) a(t) f(g(x(t))) f\left(\int_{b}^{t} b(s) d s\right)
$$

Integrating from $b$ to $t$ yields

$$
\int_{x(b)}^{x(t)} \frac{d r}{f(g(r))} \leq \alpha K^{2} f(L) \int_{b}^{t} a(s) f\left(\int_{b}^{s} b(\sigma) d \sigma\right) d s
$$

Note that $\lim _{t \rightarrow \infty} x(t)=\infty$, taking the limit as $t \rightarrow \infty$ we have

$$
\int_{x(b)}^{\infty} \frac{d r}{f(g(r))} \leq \alpha K^{2} f(L) \int_{b}^{\infty} a(t) f\left(\int_{b}^{t} b(s) d s\right) d t<\infty
$$

which contradicts (H2A). Therefore, $S(\infty, \infty)=\emptyset$.
Remark 3.7. (H2A) in Theorem 3.6 is sharp. For example, consider the differential system on $t \geq 1$

$$
\begin{align*}
x^{\prime}(t) & =\frac{1}{t^{\frac{1}{3}}} y^{\frac{1}{3}}(t)  \tag{3.4}\\
y^{\prime}(t) & =\frac{1}{t^{5}} x^{5}(t)
\end{align*}
$$

Here, $a(t)=\frac{1}{t^{\frac{1}{3}}}, b(t)=\frac{1}{t^{5}}, f(r)=r^{\frac{1}{3}}$, and $g(r)=r^{5}$. Clearly, $A=\infty$ and $B<\infty$. Moreover,

$$
\int_{1}^{\infty} \frac{d r}{f(g(r))}=\int_{1}^{\infty} \frac{d r}{r^{\frac{5}{3}}}<\infty
$$

and

$$
\int_{1}^{\infty} b(t) g\left(\int_{1}^{t} a(s) d s\right) d t<\left(\frac{3}{2}\right)^{5} \int_{1}^{\infty} \frac{d t}{t^{\frac{5}{3}}}<\infty
$$

However, $(x, y)=(t, t)$ is a $S(\infty, \infty)$ solution of system (3.4).
Remark 3.8. Theorem 3.1 extends [8] Theorem 3.1 to system (1.1). By Corollary 3.4, Theorem 3.2 and Theorem 3.3 extend [8] Theorem 3.2 to system (1.1).

## 4. The Case $A<\infty$ And $B=\infty$

Because of the symmetric feature of $x$ and $y$ in system (1.1), with the same arguments in the previous section, we have the following results.

Theorem 4.1. Suppose that $A<\infty$ and $B=\infty$. Then any eventually positive solutions of (1.1) belong to either $S(\infty, \infty)$ or $S(c, \infty)$.

Theorem 4.2. Suppose that $A<\infty$ and $B=\infty$. If $S(c, \infty) \neq \emptyset$, then

$$
\int_{a}^{\infty} a(t) f\left(g(c) \int_{a}^{t} b(s) d s\right) d t<\infty
$$

for some $c>0$.
Theorem 4.3. Suppose that $A<\infty$ and $B=\infty$. If

$$
\int_{a}^{\infty} a(t) f\left(\beta g(c) \int_{a}^{t} b(s) d s\right) d t<\infty
$$

for some $c>0$, then $S(c, \infty) \neq \emptyset$.
Combining Theorem 4.2 and Theorem 4.3, we obtain
Corollary 4.4. Suppose that $A<\infty$ and $B=\infty$. Then $S(c, \infty) \neq \emptyset$ for system (1.3) if and only if

$$
\begin{equation*}
\int_{a}^{\infty} a(t) f\left(g(c) \int_{a}^{t} b(s) d s\right) d t<\infty \tag{4.1}
\end{equation*}
$$

for some $c>0$.
Corollary 4.5. Suppose that $A<\infty, B=\infty$, and (H1A) hold. Then $S(c, \infty) \neq \emptyset$ for system (1.1) if and only if

$$
\begin{equation*}
\int_{a}^{\infty} a(t) f\left(\int_{a}^{t} b(s) d s\right) d t<\infty \tag{4.2}
\end{equation*}
$$

Theorem 4.6. Suppose that $A<\infty, B=\infty,(H 1 B)$, and (H2B) are satisfied. In addition, let (4.2) hold. Then $S(\infty, \infty)=\emptyset$.

Remark 4.7. (H2B) in Theorem 4.6 is sharp. This can be explained from Remark 3.7 by switching $x$ and $y$ in the example.

Remark 4.8. Theorem 4.1 extends [8] Theorem 4.1 to system (1.1). By Corollary 4.4, Theorem 4.1 and Theorem 4.2 extend [8] Theorem 4.2 to system (1.1).

## 5. The Case $A<\infty$ And $B<\infty$

Theorem 5.1. Suppose that $A<\infty$ and $B<\infty$. Then all eventually positive solutions of (1.1) belong to either $S(\infty, \infty)$ or $S(c, c)$.

Proof. Let $(x, y)$ be an eventually positive solution of system (1.1). Then $x^{\prime}(t)>0$ and $y^{\prime}(t)>0$ for $t \geq b$. If $\lim _{t \rightarrow \infty} x(t)=c_{1}>0$, then $x(t) \leq c_{1}$ for $t \geq b$ and

$$
\begin{aligned}
y(t) & =y(b)+\int_{b}^{t} G(s, x(s)) d s \\
& \leq y(b)+\beta \int_{b}^{t} b(s) g(x(s)) d s \\
& \leq y(b)+\beta g\left(c_{1}\right) \int_{b}^{t} b(s) d s \\
& \leq y(b)+\beta g\left(c_{1}\right) B<\infty
\end{aligned}
$$

which implies that $\lim _{t \rightarrow \infty} y(t)=c_{2}>0$. Similarly, if $\lim _{t \rightarrow \infty} y(t)=c_{2}>0$, then $\lim _{t \rightarrow \infty} x(t)=c_{1}>0$.
Theorem 5.2. The solution class $S(c, c) \neq \emptyset$ if and only if $A<\infty$ and $B<\infty$.
Proof. Let $(x, y)$ be an eventually positive class $S(c, c)$ solution of system (1.1). Then $x^{\prime}(t)>0$ and $y^{\prime}(t)>0$ for $t \geq b$, also, $\lim _{t \rightarrow \infty} x(t)=c_{1}>0$ and $\lim _{t \rightarrow \infty} y(t)=c_{2}>0$. In view of

$$
\begin{aligned}
x(t) & =x(b)+\int_{b}^{t} F(s, y(s)) d s \\
& \geq \int_{b}^{t} a(s) f(y(s)) d s \\
& \geq f(y(b)) \int_{b}^{t} a(s) d s,
\end{aligned}
$$

we have $A<\infty$. The proof of $B<\infty$ is similar.
Conversely, for two real numbers $c>0$ and $d>0$, we have

$$
\int_{a}^{\infty} a(t) f(2 c) d t<\infty, \quad \int_{a}^{\infty} b(t) g(2 d) d t<\infty
$$

Pick $T>b$ large enough such that

$$
\int_{T}^{\infty} a(t) f(2 c) d t<\frac{d}{\alpha}, \quad \int_{T}^{\infty} b(t) g(2 d) d t<\frac{c}{\beta}
$$

Let $C B[T, \infty) \times C B[T, \infty)$ be the space of all continuous and bounded function pairs with the usual pointwise ordering $\leq$. Define a subset of $C B[T, \infty) \times C B[T, \infty)$ as

$$
X=\{(x, y) \in C B[T, \infty) \times C B[T, \infty): d \leq x(t) \leq 2 d, c \leq y(t) \leq 2 c, t \geq T\}
$$

Clearly, for any subset $\Omega$ of $X, \inf \Omega \in X$ and $\sup \Omega \in X$. Consider an operator $J: X \rightarrow C B[T, \infty) \times$ $C B[T, \infty)$ with

$$
\begin{aligned}
& (J x)(t)=d+\int_{T}^{t} F(s, y(s)) d s \\
& (J y)(t)=c+\int_{T}^{t} G(s, x(s)) d s
\end{aligned}
$$

The operator $J$ satisfies all the assumptions of Knaster's fixed-point theorem [5]: $J$ maps $X$ into $X$ and preserve the order. Indeed, if $(x, y) \in X$, then

$$
d \leq(J x)(t) \leq d+\alpha \int_{T}^{\infty} a(t) f(y(t)) d t \leq d+\alpha \int_{T}^{\infty} a(t) f(2 c) d t \leq 2 d
$$

and

$$
c \leq(J y)(t) \leq c+\beta \int_{T}^{\infty} b(t) g(x(t)) d t \leq c+\beta \int_{T}^{\infty} b(t) g(2 d) d t \leq 2 c
$$

By Knaster's fixed-point theorem, $J$ has a fixed-point in $X$, let it be $(\bar{x}, \bar{y}) \in X$. Then

$$
\begin{aligned}
& \bar{x}^{\prime}(t)=d+\int_{T}^{t} F(s, \bar{y}(s)) d s \\
& \bar{y}^{\prime}(t)=c+\int_{T}^{t} G(s, \bar{x}(s)) d s
\end{aligned}
$$

It is easy to check that $(\bar{x}, \bar{y})$ is a class $S(c, c)$ solution of system (1.1).
Theorem 5.3. Suppose that $A<\infty$ and $B<\infty$. Then the solution class $S(\infty, \infty)=\emptyset$ if one of the following two conditions is satisfied:
(1): (H1A) and (H2A),
(2): (H1B) and (H2B).

Proof. Note that $A<\infty$ and $B<\infty$ imply (3.3) and (4.2). The rest proof is similar to that of Theorem 3.6 and Theorem 4.6.

Remark 5.4. (H2A) and (H2B) are sharp in Theorem 5.3. For example, consider the differential system on $t \geq 1$

$$
\begin{align*}
x^{\prime}(t) & =\frac{1}{t^{3}} y^{3}(t) \\
y^{\prime}(t) & =\frac{1}{t^{5}} x^{5}(t) \tag{5.1}
\end{align*}
$$

Here, $a(t)=\frac{1}{t^{3}}, b(t)=\frac{1}{t^{5}}, f(r)=r^{3}$, and $g(r)=r^{5}$. Clearly, $A<\infty$ and $B<\infty$. Moreover,

$$
\int_{1}^{\infty} \frac{d r}{f(g(r))}=\int_{1}^{\infty} \frac{d r}{g(f(r))}=\int_{1}^{\infty} \frac{d r}{r^{15}}<\infty
$$

However, $(x, y)=(t, t)$ is a class $S(\infty, \infty)$ solution of system (5.1).
Remark 5.5. Theorem 5.1 and Theorem 5.2 extend Theorem 5.1 and Theorem 5.2 in [8] to nonseparable differential system (1.1), respectively.

## References

[1] I. Bachar and H. Mâagli, Existence and global asymptotic behavior of positive solutions for combined secondorder differential equations on the half-line, Adv. Nonlinear Anal., 5 (2016), 205-222. 1
[2] M. Cecchi, Z. Došlá, M. Marini, and I. Vrkoč, Integral conditions for nonoscillation of second order nonlinear differential equations, Nonlinear Analysis, 64(2006), 1278-1289. 1
[3] M. Cecchi, Z. Došlá, I. Kiguradze, and M. Marini, On nonnegative solutions of singular boundary-value problems for Emden-Fowler-type differential systems, Differential Integral Equations, 20 (2007) 1081-1106. 1
[4] Z. Došlá and K. Fujimoto, Asymptotic problems for nonlinear ordinary differential equations with $\varphi$-Laplacian, J. Math. Anal. Appl., 484 (2020), Article ID 123674. 1
[5] I. Györi and G. Ladas, Oscillation Theory of Delay Differential Equations With Applications, Clarendon, Oxford, 1991. 5
[6] E. R. Kaufmann, Existence of positive solutions to a second-order differential equation at resonance, Communications in Applied Analysis, 19 (2015) 505-514. 1
[7] W. Li and S. Cheng, Limiting behaviours of non-oscillatory solutions of a pair of coupled nonlinear differential equations, Proceedings of the Edinburgh Mathematical Society, 43 (2000) 457-473. 1
[8] W. Li, Classification schemes for positive solutions of nonlinear differential systems, Mathematical and Computer Modelling, 35 (2002) 411-418. 1, 1, 2.2, 3.8, 4.8, 5.5
[9] L. Wang, On monotonic solutions of systems of nonlinear second order differential equations, Nonlinear Analysis, 70 (2009) 2563-2574. 1
[10] L. Wang and R. McKee, Nonoscillatory solutions of second-order differential equations without monotonicity assumptions, J. Appl. Math., 2012, Article ID 313725. 1
[11] L. Wang, Extensibility and boundedness of solutions of second-order nonlinear differential equations, Dynamics of Continuous, Discrete and Impulsive Systems Series A: Mathematical Analysis, 20 (2013) 121-130. 1
[12] P. J. Y. Wong and R. P. Agarwal, Oscillatory behavior of solutions of certain second order nonlinear differential equations, J. Math. Anal. Appl., 198 (1998) 337-354. 1
[13] X. Zhang and M. Feng, Positive solutions for a second-order differential equation with integral boundary conditions and deviating arguments, Boundary Value Problems, 2015, Article ID 222. 1


[^0]:    *Corresponding author
    Email address: lwang@ucmo.edu (Lianwen Wang 1)

