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# Existence and Uniqueness Solutions of System Caputo-type Fractional-Order Boundary Value Problems Using Monotone Iterative Method 

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#### Abstract

In this paper, we investigate the existence and uniqueness solutions of nonlinear boundary value problems for system of Caputo type nonlinear fractional differential equations of the form: $$
\left\{\begin{aligned} { }^{c} D_{a^{+}}^{q ; \psi} u_{i}(t)= & F_{i}\left(t, u_{1}(t), u_{2}(t)\right) \quad t \in J=[a, b] \\ & \phi\left(v_{i}(a), v_{i}(b)\right)=0 \end{aligned}\right.
$$

To develop a monotone iterative technique by introducing upper and lower solutions to Caputo type fractional differential equations with nonlinear boundary conditions. The monotone method yield monotone sequences which converges to uniformly and monotonically to extremal solutions.


Keywords: $\psi$-Caputo fractional derivative, upper and lower solutions, monotone iterative method. 2010 MSC: 26A33, 26A48, 34A08.

## 1. Introduction

Fractional differential equations or fractional differential systems have numerous applications in diverse and widespread field of science and technology[4, 10, 22]. The study of fractional calculus and its applications see more details $[12,13,20]$. The approach to obtain existence and uniqueness of solutions for the nonlinear fractional differential systems in general has been through fixed point theorem method $[3,9,16,23,24,25$,

[^0]26]. In this paper to investigate the existence and uniqueness using the method of lower and upper solutions combined with the monotone iterative technique [5, 6, 24, 28, 29].

The monotone method is useful for nonlinear equations and systems because it reduces the problem to sequences of linear equations. Specifically, if the nonlinear system is unwieldy, too difficult to solve explicitly, then the monotone method may be beneficial. If one can find upper and lower solutions to the original system that are less unwieldy and satisfy the particular requirements, then the monotone method implements a technique for constricting sequences from these upper and lower solutions. These sequences are solutions to linear equations and converge uniformly and monotonically to maximal and minimal solutions $[11,12,14,16,17,18,19,25]$.

Motivated by the work see [8], we determine the existence criteria of extremal solution for following system $\psi$-Caputo type fractional differential equations in a Caputo sense with nonlinear boundary conditions

$$
\left\{\begin{array}{c}
{ }^{c} D_{a^{+}}^{q ; \psi} u_{i}(t)=F_{i}\left(t, u_{1}(t), u_{2}(t)\right) \quad t \in J=[a, b],  \tag{1.1}\\
\\
\phi\left(v_{i}(a), v_{i}(b)\right)=0 .
\end{array}\right.
$$

The rest of paper is arranged in the following way.
In section 2, definitions and basic results are discussed that plays vital role in the main results. These results are useful in main results proving that the sequences developed in the generalized monotone method converge to coupled minimal and maximal solutions of the non-linear system of fractional differential equation. Finally under uniqueness assumption, we prove that there exists a unique solution to the non-linear system of $\psi$ Caputo fractional differential equation.

## 2. Preliminaries

In this section, we recall some known definitions and known results which are useful to develop our main result.
Definition 2.1[1, 4] The $\psi$-Riemann-Liouville fractional integral of order $q$ is defined by

$$
I_{a+}^{q ; \psi} u(t)=\frac{1}{\Gamma(q)} \int_{0}^{t} \psi^{\prime}(\psi(t)-\psi(s))^{q-1} u(s) d s, t>a
$$

Definition 2.2[1] Let $\psi, u \in C^{n}(J, \mathbb{R})$. The $\psi$-Riemann-Liouville derivative of order of a function $u$ with $(n-1<q \leq n)$ can be written as

$$
\begin{aligned}
D_{a+}^{q ; \psi} u(t) & =\left(\frac{D_{t}}{\psi^{\prime}(t)}\right)^{n} I_{a+}^{n-q ; \psi} u(t) \\
& =\frac{1}{\Gamma(n-q)}\left(\frac{D_{t}}{\psi^{\prime}(t)}\right)^{n} \int_{0}^{t} \psi^{\prime}(\psi(t)-\psi(s))^{n-q-1} u(s) d s
\end{aligned}
$$

where $n=[q]+1(n \in \mathbb{N})$, and $D_{t}=\frac{d}{d t}$.
Definition 2.2[1] Let $\psi, u \in C^{n}(J, \mathbb{R})$. The $\psi$-Caputo derivative of order of a function $u$ with $(n-1<$ $q \leq n$ ) can be written as

$$
D_{a+}^{q ; \psi} u(t)=I_{a+}^{n-q ; \psi} u_{\psi}^{[n]}(t)
$$

where $u_{\psi}^{[n]}(t)=\left(\frac{D_{t}}{\psi^{\prime}(t)}\right)^{n} u(t), n=[q]+1$ for $q \notin \mathbb{N}$ and $n=q$ for $q \in \mathbb{N}$.
One has

$$
{ }^{c} D_{a^{+}}^{q ; \psi} u(t)=\left\{\begin{array}{c}
\int_{0}^{t} \psi^{\prime}(\psi(t)-\psi(s))^{n-q-1} u_{\psi}^{[n]}(s) d s, \quad \text { if } q \notin \mathbb{N} \\
u_{\psi}^{[n]}(t), \quad \text { if } q \in \mathbb{N}
\end{array}\right.
$$

Definition 2.3[2] One and two parameter Mittag-Leffler function is defined as

$$
\begin{aligned}
E_{q}(t) & =\sum_{k=0}^{\infty} \frac{(t)^{k}}{\Gamma(q k+1)} \quad t \in \mathbb{R}, q>0 \\
E_{q, \beta}(t) & =\sum_{k=0}^{\infty} \frac{(t)^{k}}{\Gamma(q k+\beta)} \quad q, \beta>0, t \in \mathbb{R}
\end{aligned}
$$

Lemma 2.1[1] Let $p, q>0$, and $u \in C(J, \mathbb{R})$, for every $t \in J$
i. ${ }^{c} D_{a^{+}}^{q ; \psi} I_{a^{+}}^{q ; \psi} u(t)=u(t)$,
ii. $I_{a^{+}}^{q ; \psi_{c}} D_{a^{+}}^{q ; \psi} u(t)=u(t)-u(a), 0<q \leq 1$.
iii. $I_{a^{+}}^{q ; \psi}(\psi(t)-\psi(a))^{p-1}=\frac{\Gamma(p)}{\Gamma(p-q)}(\psi(t)-\psi(a))^{p+q-1}$,
iv. ${ }^{c} D_{a^{+}}^{q ; \psi}(\psi(t)-\psi(a))^{p-1}=\frac{\Gamma(p)}{\Gamma(p-q)}(\psi(t)-\psi(a))^{p-q-1}$,
v. ${ }^{c} D_{a^{+}}^{q ; \psi}(\psi(t)-\psi(a))^{k}=0, \forall k<n \in \mathbb{N}$

Lemma 2.2[27] Let $q \in(0,1)$ and $x \in \mathbb{R}$, one has i. $E_{q, 1}$ and $E_{q, q}$ are non-negative. ii. $E_{q, 1}(x) \leq$ $1, E_{q, q}(x) \leq \frac{1}{\Gamma(q)}$, for any $x<0$.

Lemma 2.3[8] Let $q \in(0,1), \lambda \in \mathbb{R}$ and $g \in C(J, \mathbb{R})$, then the linear problem

$$
\left\{\begin{array}{c}
{ }^{c} D_{a^{+}}^{q ; \psi} u(t)+\lambda u(t)=g(t), \quad t \in J . \\
u(a)=u_{a}
\end{array}\right.
$$

has a unique solution as

$$
\begin{aligned}
u(t) & =u_{a} E_{q, 1}\left(-\lambda(\psi(t)-\psi(a))^{q}\right) \\
& +\int_{0}^{t} \psi^{\prime}(\psi(t)-\psi(s))^{q-1} E_{q, q}\left(-\lambda(\psi(t)-\psi(a))^{q}\right) g(s) d s
\end{aligned}
$$

where $E_{p, q}($.$) is the two parametric Mittag-Leffler function$
Lemma 2.4 [Comprising result][8] Let $q \in(0,1)$ and $\lambda \in \mathbb{R}$ if $\gamma \in C(J, \mathbb{R})$,

$$
\left\{\begin{array}{c}
{ }^{c} D_{a^{+}}^{q ; \psi} \gamma(t) \geq-\lambda \gamma(t), \quad t \in(a, b] \\
\gamma(a) \geq 0
\end{array}\right.
$$

then $\gamma(t) \geq 0$ for all $t \in J$.

## 3. Main Result

In this section, we develop a monotone method for the system $\psi$-Caputo fractional differential equations (3.7) using coupled lower and upper solutions respectively.

Defination 3.1 The functions $f_{i} \in C\left(J, \mathbb{R}\right.$ such that ${ }^{c} D_{a^{+}}^{q ; \psi} f_{i}(t)$ exist and is continuous on $J$ and is known to be a solutions (1.1).Further, $f_{i}$ gives the statistics of the equation ${ }^{c} D_{a+}^{q ; \psi} u_{i}(t)=F_{i}\left(t, u_{1}(t), u_{2}(t)\right)$, for each $t \in J$ and the nonlinear boundary conditions

$$
\phi\left(f_{i}(a), f_{i}(b)\right)=0
$$

Definition 3.2 If the functions $v_{i}(x, t), \quad w_{i}(x, t) \in C^{2, q}\left[Q_{T}, \mathbb{R}\right]$ are called the lower and upper solutions of if

$$
\left\{\begin{array}{r}
{ }^{c} D_{a^{+}}^{q ; \psi} v_{i}(t) \leq F_{i}\left(t, v_{1}(t), v_{2}(t)\right) \quad t \in[a, b] \\
\phi\left(v_{i}(a), v_{i}(b)\right) \leq 0
\end{array}\right.
$$

$$
\left\{\begin{array}{c}
{ }^{c} D_{a^{+}}^{q ; \psi} w_{i}(t) \geq F_{i}\left(t, w_{1}(t), w_{2}(t)\right) \quad t \in[a, b] \\
\phi\left(w_{i}(a), w_{i}(b)\right) \geq 0
\end{array}\right.
$$

Theorem 3.1 Let $F: J \times \mathbb{R} \rightarrow \mathbb{R}$ be continuous. Assume that
(i) There exist $v_{i}(t)$ and $w_{i}(t)$ as lower and upper solutions of problem (1.1) in $C(J, \mathbb{R})$ respectively, with $v_{i}(t) \leq w_{i}(t), \quad t \in J$.
(ii) There exist a constant $k_{i}>0$ with

$$
F_{i}\left(t, u_{2}\right)-F_{i}\left(t, u_{1}\right) \geq-k_{i}\left(u_{2}-u_{1}\right) \quad \text { for } \quad v_{i}(t) \leq u_{1} \leq u_{2} \leq w_{i}(t), t \in J
$$

(iii) There exists nonnegative constants $M, N$ with $v_{i}(a) \leq x_{1} \leq x_{2} \leq w_{i}(a), v_{i}(b) \leq y_{1} \leq y_{2} \leq w_{i}(b)$, such that

$$
\phi_{i}\left(x_{2}, y_{2}\right)-\phi_{i}\left(x_{1}, y_{1} \leq M\left(x_{2}-x_{1}\right)-N\left(y_{2}-y_{1}\right)\right.
$$

Then there exist monotone sequences $\left\{v_{i}^{n}(t)\right\}$ and $\left\{w_{i}^{n}(t)\right\}$ such that $v_{i}^{n}(t) \rightarrow v_{i}(t)$ and $w_{i}^{n}(t) \rightarrow w_{i}(t)$ as $n \rightarrow \infty$ uniformly on $J$, to the extremal solutions of (1.1) in the sector $\left[v_{i}, w_{i}\right]$ where

$$
\left[v_{i}, w_{i}\right]=\left\{u_{i} \in C(J, \mathbb{R}): v_{i}(t) \leq u_{i}(t) \leq w_{i}(t), t \in J\right\}
$$

## Proof.

We construct the sequences $\left\{v_{i}^{n+1}(t)\right\}$ and $\left\{w_{i}^{n+1}(t)\right\}$ and $k_{i}>0$, we consider the following fractional differential equations

$$
\begin{gather*}
\left\{\begin{array}{c}
{ }^{c} D_{a^{+}}^{q ; \psi} v_{i}^{n+1}(t)=F_{i}\left(t, v_{i}^{n}(t)\right)-k\left(v_{i}^{n+1}(t)-v_{i}^{n}(t)\right) \\
v_{i}^{n+1}(a)=v_{i}^{n}(a)-\frac{1}{c} \phi\left(v_{i}^{n}(a), v_{i}^{n}(b)\right)
\end{array}\right.  \tag{3.1}\\
\left\{\begin{array}{c}
{ }^{c} D_{a^{+}}^{q ; \psi} w_{i}^{n+1}(t)=F_{i}\left(t, w_{i}^{n}(t)\right)-k\left(w_{i}^{n+1}(t)-w_{i}^{n}(t)\right) \quad t \in J, \\
\left.w_{i}^{n+1}(a)=w_{i}^{n}(a)\right)-\frac{1}{c} \phi\left(w_{i}^{n}(a), w_{i}^{n}(b)\right)
\end{array}\right. \tag{3.2}
\end{gather*}
$$

By Lemma 3 and equation (3.1),(3.2)preserve at most one solution in $C(J, \mathbb{R}$ we have

$$
\begin{array}{r}
\left.v_{i}^{n+1}(t)=\left(v_{i}^{n}(a)\right)-\frac{1}{c} \phi\left(v_{i}^{n}(a), v_{i}^{n}(b)\right)\right) E_{q, 1}\left(-k_{i}\left((\psi)_{i}(t)-\psi_{i}(a)\right)^{q}\right) \\
+\int_{a}^{t} \psi_{i}^{\prime}(s)\left(\psi_{i}(t)-\psi_{i}(a)\right)^{q-1} E_{q, q}\left(-k_{i}\left(\psi_{i}(t)-\psi_{i}(s)\right)^{q}\right)\left(F_{i}\left(s, v_{i}^{n}(s)\right)+k_{i}\left(v_{i}^{n+1}(s)\right)\right) d s \quad t \in J \\
\left.w_{i}^{n+1}(t)=\left(w_{i}^{n}(a)\right)-\frac{1}{c} \phi\left(w_{i}^{n}(a), w_{i}^{n}(b)\right)\right) E_{q, 1}\left(-k_{i}\left((\psi)_{i}(t)-\psi_{i}(a)\right)^{q}\right) \\
+\int_{a}^{t} \psi_{i}^{\prime}(s)\left(\psi_{i}(t)-\psi_{i}(a)\right)^{q-1} E_{q, q}\left(-k_{i}\left(\psi_{i}(t)-\psi_{i}(s)\right)^{q}\right)\left(F_{i}\left(s, w_{i}^{n}(s)\right)+k_{i}\left(w_{i}^{n+1}(s)\right)\right) d s \quad t \in J
\end{array}
$$

Step 1: The sequences $\left\{v_{i}^{n+1}(t)\right\},\left\{w_{i}^{n+1}(t)\right\}(n \geq 1)$ are lower and upper solutions of () respectively. We prove that $v_{i}^{0}(t) \leq v_{i}^{1}(t)$. Let $\rho_{i}(t)=v_{i}^{1}(t)-v_{i}^{0}(t)$. Then equation (3.1) and Definition 3.2, we have

$$
\begin{aligned}
{ }^{c} D_{a^{+}}^{q ; \psi} \rho_{i}(t) & ={ }^{c} D_{a^{+}}^{q ; \psi} v_{i}^{1}(t)-{ }^{c} D_{a^{+}}^{q ; \psi} v_{i}^{0}(t) \\
& \left.\geq F_{i}\left(t, v_{i}^{0}(t)\right)-k_{i}\left(v_{i}^{1}(t)-v_{i}^{0}(t)\right)-F_{i}\left(t, v_{i}^{0}(t)\right)\right) \\
& =-k_{i} \rho_{i}(t)
\end{aligned}
$$

Since $\rho_{i}(a)=-\frac{1}{c} \phi\left(v_{i}^{0}(a), v_{i}^{0}(b)\right) \geq 0, \rho_{i}(t) \geq 0$, for $t \in J$ by Lemma 4. Thus $v_{i}^{0}(t) \leq v_{i}^{1}(t)$. Assume that $v_{i}^{k-1}(t) \leq v_{i}^{k}(t)$. Now we show that $v_{i}^{k}(t) \leq v_{i}^{k+1}(t)$. Let $\rho_{i}(t)=v_{i}^{k}(t)-v_{i}^{k+1}(t)$

$$
\begin{aligned}
{ }^{c} D_{a^{+}}^{q ; \psi} \rho_{i}(t) & ={ }^{c} D_{a^{+}}^{q ; \psi} v_{i}^{k}(t)-{ }^{c} D_{a^{+}}^{q ; \psi} v_{i}^{k+1}(t) \\
& \left.\geq F_{i}\left(t, v_{i}^{k}(t)\right)-k_{i}\left(v_{i}^{k+1}(t)-v_{i}^{k}(t)\right)-F_{i}\left(t, v_{i}^{k}(t)\right)\right) \\
& =-k_{i} \rho_{i}(t)
\end{aligned}
$$

Since $\rho_{i}(a)=-\frac{1}{c} \phi\left(v_{i}^{k}(a), v_{i}^{k}(b)\right) \geq 0, \rho_{i}(t) \geq 0$, for $t \in J$ by Lemma 4. Thus $v_{i}^{k}(t) \leq v_{i}^{k+1}(t)$. Hence by mathematical induction, we have

$$
\begin{equation*}
v_{i}^{0}(t) \leq v_{i}^{1}(t) \leq \ldots \leq v_{i}^{k}(t) \leq v_{i}^{k+1}(t) \leq \ldots \leq v_{i}^{n}(t) \tag{3.3}
\end{equation*}
$$

Next, we prove that $w_{i}^{1}(t)-w_{i}^{0}(t), t \in J$. Let $\rho_{i}(t)=w_{i}^{0}(t)-w_{i}^{1}(t)$. Then equation (3.1) and Definition 3.2, we have

$$
\begin{aligned}
{ }^{c} D_{a^{+}}^{q ; \psi} \rho_{i}(t) & ={ }^{c} D_{a^{+}}^{q ; \psi} w_{i}^{0}(t)-{ }^{c} D_{a^{+}}^{q ; \psi} w_{i}^{1}(t) \\
& \geq F_{i}\left(t, w_{i}^{1}(t)\right)-k_{i}\left(w_{i}^{0}(t)-w_{i}^{1}(t)\right)-F_{i}\left(t, w_{i}^{1}(t)\right) \\
& =-k_{i} \rho_{i}(t)
\end{aligned}
$$

Since $\rho_{i}(a)=-\frac{1}{c} \phi\left(w_{i}^{0}(a), w_{i}^{0}(b)\right) \geq 0, \rho_{i}(t) \geq 0$, for $t \in J$ by Lemma 4. Thus $w_{i}^{1}(t) \leq w_{i}^{0}(t)$. Assume that $w_{i}^{k}(t) \leq w_{i}^{k-1}(t)$. Now we show that $w_{i}^{k+1}(t) \leq w_{i}^{k}(t)$. Let $\rho_{i}(t)=w_{i}^{k+1}(t)-w_{i}^{k}(t)$

$$
\begin{aligned}
{ }^{c} D_{a^{+}}^{q ; \psi} \rho_{i}(t) & ={ }^{c} D_{a^{+}}^{q ; \psi} w_{i}^{k+1}(t)-{ }^{c} D_{a^{+}}^{q ; \psi} w_{i}^{k}(t) \\
& \left.\leq F_{i}\left(t, w_{i}^{k+1}(t)\right)-k_{i}\left(w_{i}^{k+1}(t)-w_{i}^{k}(t)\right)-F_{i}\left(t, w_{i}^{k+1}(t)\right)\right) \\
& =-k_{i} \rho_{i}(t)
\end{aligned}
$$

Since $\rho_{i}(a)=-\frac{1}{c} \phi\left(w_{i}^{k+1}(a), w_{i}^{k+1}(b)\right) \geq 0, \rho_{i}(t) \geq 0$, for $t \in J$ by Lemma 4. Thus $w_{i}^{k+1}(t) \leq w_{i}^{k}(t)$. Hence by mathematical induction, we have

$$
\begin{equation*}
w_{i}^{n}(t) \leq w_{i}^{n-1}(t) \leq \ldots \leq w_{i}^{k}(t) \leq w_{i}^{k-1}(t) \leq \ldots \leq w_{i}^{1}(t) \leq w_{i}^{0}(t) \tag{3.4}
\end{equation*}
$$

Now to Prove that $v_{i}^{1}(t) \leq w_{i}^{1}(t)$. Let $\rho_{i}(t)=w_{i}^{1}(t)-v_{i}^{1}(t)$. Using equation (3.1) and (3.2) together with assumption (ii) and (iii) we have

$$
\begin{aligned}
{ }^{c} D_{a^{+}}^{q ; \psi} \rho_{i}(t) & =F_{i}\left(t, w_{i}^{0}(t)\right)-F_{i}\left(t, v_{i}^{0}(t)\right)-k_{i}\left(w_{i}^{1}(t)-w_{i}^{0}(t)\right)+k_{i}\left(v_{i}^{1}(t)-v_{i}^{0}\right) \\
& \geq-k_{i}\left(w_{i}^{0}(t)-v_{i}^{0}(t)\right)-k_{i}\left(w_{i}^{1}(t)-w_{i}^{0}(t)\right)+k_{i}\left(v_{i}^{1}(t)-v_{i}^{0}(t)\right) \\
& =-k_{i} \rho_{i}(t)
\end{aligned}
$$

Since

$$
\begin{aligned}
\rho_{i}(a) & =\left(w_{i}^{0}(a)-v_{i}^{0}(t)\right)-\frac{1}{c}\left(\phi\left(w_{i}^{0}(a), w_{i}^{0}(b)\right)-\phi\left(v_{i}^{0}(a), v_{i}^{0}(b)\right)\right) \\
& \geq \frac{d}{c}\left(\left(w_{i}^{0}(b)-v_{i}^{0}(b)\right.\right. \\
& \geq 0
\end{aligned}
$$

we have $v_{i}^{1}(t) \leq w_{i}^{1}(t), t \in J$ by Lemma 4. Hence $v_{i}^{0}(t) \leq v_{i}^{1}(t) \leq w_{i}^{1}(t) \leq w_{i}^{0}(t)$.
By mathematical inductions and equations (3.3),(3.4) we get

$$
\begin{equation*}
v_{i}^{0}(t) \leq v_{i}^{1}(t) \leq \ldots \leq v_{i}^{n}(t) \leq w_{i}^{n}(t) \leq \ldots \leq w_{i}^{1}(t) \leq w_{i}^{0}(t) \tag{3.5}
\end{equation*}
$$

We prove that $v_{i}^{0}(t), w_{i}^{0}(t)$ are extremum solutions of (1.1). Since $v_{i}^{0}$ and $w_{i}^{0}$ are lower and upper solutions of (1.1), assumptions (ii) and (iii), we get

$$
\begin{aligned}
{ }^{c} D_{a^{+}}^{q ; \psi} v_{i}^{0}(t) & =F_{i}\left(t, v_{i}^{0}(t)\right)-k_{i}\left(v_{i}^{1}(t)-v_{i}^{0}(t)\right) \\
& \leq F_{i}\left(t, v_{i}^{1}(t)\right)
\end{aligned}
$$

and

$$
\begin{aligned}
\phi\left(v_{i}^{1}(a), v_{i}^{1}(b)\right) & \leq \phi\left(v_{i}^{0}(a), v_{i}^{0}(b)+c\left(v_{i}^{1}(a)-v_{i}^{0}(a)\right)-d\left(v_{i}^{1}(b)-v_{i}^{0}(b)\right)\right. \\
& =-d\left(v_{i}^{1}(b)-v_{i}^{0}(b)\right) \\
& \leq 0 \\
{ }^{c} D_{a^{+}}^{q ; \psi} w_{i}^{0}(t) & =F_{i}\left(t, w_{i}^{0}(t)\right)-k_{i}\left(w_{i}^{1}(t)-w_{i}^{0}(t)\right) \\
& \geq F_{i}\left(t, w_{i}^{1}(t)\right)
\end{aligned}
$$

and

$$
\begin{aligned}
\phi\left(w_{i}^{1}(a), w_{i}^{1}(b)\right) & \geq \phi\left(w_{i}^{0}(a), w_{i}^{0}(b)+c\left(w_{i}^{1}(a)-w_{i}^{0}(a)\right)-d\left(w_{i}^{1}(b)-w_{i}^{0}(b)\right)\right. \\
& =-d\left(w_{i}^{1}(b)-w_{i}^{0}(b)\right) \\
& \geq 0
\end{aligned}
$$

Therefore, $v_{i}^{1}(t), w_{i}^{1}(t)$ is lower and upper solution of (1.1)respectively. By induction,Hence $v_{i}^{n}(t)$, $w_{i}^{n}(t)$ are lower and upper solutions of (1.1) respectively.

Step 2: $v_{i}^{n} \rightarrow v_{i}$ and $w_{i}^{n} \rightarrow w_{i}$
First, we prove that $\left\{v_{i}^{n}\right\}$ is uniformly bounded. By considering supposition Hypothesis 2, we have

$$
F_{i}\left(t, v_{i}^{0}(t)\right)+k_{i} v_{i}^{0}(t) \leq F_{i}\left(t, v_{i}^{n}(t)\right)+k_{i} v_{i}^{n}(t) \leq F_{i}\left(t, w_{i}^{0}(t)\right)+k_{i} w_{i}^{0}(t), \quad t \in J
$$

That is

$$
\begin{aligned}
0 & \leq F_{i}\left(t, v_{i}^{n}(t)\right)-F_{i}\left(t, v_{i}^{0}(t)\right)+k_{i}\left(v_{i}^{n}(t)-v_{i}^{0}(t)\right) \\
& \leq F_{i}\left(t, w_{i}^{0}(t)\right)-F_{i}\left(t, v_{i}^{0}(t)\right)+k_{i}\left(w_{i}^{0}(t)-v_{i}^{0}(t)\right)
\end{aligned}
$$

Hence, we have

$$
\begin{aligned}
\left|F_{i}\left(t, v_{i}^{n}(t)\right)-F_{i}\left(t, v_{i}^{0}(t)\right)+k_{i}\left(v_{i}^{n}(t)-v_{i}^{0}(t)\right)\right| & \leq \mid F_{i}\left(t, w_{i}^{0}(t)\right)-F_{i}\left(t, v_{i}^{0}(t)\right) \\
& +k_{i}\left(w_{i}^{0}(t)-v_{i}^{0}(t)\right) \mid
\end{aligned}
$$

Thus

$$
\begin{aligned}
\mid F_{i}\left(t, v_{i}^{n}(t)\right)+k_{i}\left(v_{i}^{n}(t) \mid\right. & \leq\left|F_{i}\left(t, v_{i}^{n}(t)\right)-F_{i}\left(t, v_{i}^{0}(t)\right)+k_{i}\left(v_{i}^{n}(t)-v_{i}^{0}(t)\right)\right| \\
& +\mid F_{i}\left(t, v_{i}^{0}(t)\right)+k_{i}\left(v_{i}^{0}(t) \mid\right. \\
& \leq\left|F_{i}\left(t, w_{i}^{0}(t)\right)-F_{i}\left(t, v_{i}^{0}(t)\right)+k_{i}\left(w_{i}^{0}(t)-v_{i}^{0}(t)\right)\right| \\
& +\mid F_{i}\left(t, v_{i}^{0}(t)\right)+k_{i}\left(v_{i}^{0}(t) \mid\right. \\
& +\leq 2 \mid F_{i}\left(t, v_{i}^{0}(t)\right)+k_{i}\left(v_{i}^{0}(t)|+| F_{i}\left(t, v_{i}^{0}(t)\right)+k_{i}\left(v_{i}^{0}(t) \mid .\right.\right.
\end{aligned}
$$

Since $v_{i}^{0}, F_{i}$ are continuous on $J$, we can see a constant $C$ independent of $n$ with

$$
\begin{equation*}
\mid F_{i}\left(t, v_{i}^{n}(t)\right)+k_{i}\left(v_{i}^{n}(t) \mid \leq C\right. \tag{3.6}
\end{equation*}
$$

Furthermore, from Hypothesis 3, we have

$$
v_{i}^{0}(a)-\frac{1}{c} \phi\left(v_{i}^{0}(a), v_{i}^{0}(b)\right) \leq v_{i}^{n}(a)-\frac{1}{c} \phi\left(w_{i}^{0}(a), w_{i}^{0}(b)\right) \leq w_{i}^{0}(a)-\frac{1}{c} \phi\left(v_{i}^{0}(a), v_{i}^{0}(b)\right)
$$

That is

$$
\begin{aligned}
0 & \leq v_{i}^{n}(a)-v_{i}^{0}(a)-\frac{1}{c} \phi\left(v_{i}^{n}(a), v_{i}^{n}(b)\right)-\phi\left(v_{i}^{0}(a), v_{i}^{0}(b)\right) \\
& \leq w_{i}^{0}(a)-v_{i}^{0}(a)-\frac{1}{c} \phi\left(w_{i}^{n}(0), w_{i}^{0}(b)\right)-\phi\left(v_{i}^{0}(a), v_{i}^{0}(b)\right)
\end{aligned}
$$

Hence, we have

$$
\begin{aligned}
& \left|v_{i}^{n}(a)-v_{i}^{0}(a)-\frac{1}{c} \phi\left(v_{i}^{n}(a), v_{i}^{n}(b)\right)-\phi\left(v_{i}^{0}(a), v_{i}^{0}(b)\right)\right| \\
& \quad \leq\left|v_{i}^{n}(a)-v_{i}^{0}(a)-\frac{1}{c} \phi\left(v_{i}^{n}(a), v_{i}^{n}(b)\right)-\phi\left(v_{i}^{0}(a), v_{i}^{0}(b)\right)\right| \\
& \quad \leq\left|v_{i}^{n}(a)-v_{i}^{0}(a)-\frac{1}{c} \phi\left(v_{i}^{n}(a), v_{i}^{n}(b)\right)-\phi\left(v_{i}^{0}(a), v_{i}^{0}(b)\right)\right| .
\end{aligned}
$$

Thus

$$
\begin{aligned}
\left|v_{i}^{n}(a)-\frac{1}{c} \phi\left(v_{i}^{n}(a), v_{i}^{n}(b)\right)\right| & \leq\left|v_{i}^{n}(a)-v_{i}^{0}(a)-\frac{1}{c} \phi\left(v_{i}^{n}(a), v_{i}^{n}(b)\right)-\phi\left(v_{i}^{0}(a), v_{i}^{0}(b)\right)\right| \\
& +\left|v_{i}^{0}(a)-\frac{1}{c} \phi\left(v_{i}^{0}(a), v_{i}^{0}(b)\right)\right| \\
& \leq 2\left|v_{i}^{0}(a)-\frac{1}{c} \phi\left(v_{i}^{0}(a), v_{i}^{0}(b)\right)\right|+\left|w_{i}^{0}(a)-\frac{1}{c} \phi\left(w_{i}^{0}(a), w_{i}^{0}(b)\right)\right| .-
\end{aligned}
$$

Since $v_{i}^{0}, w_{i}^{0}$ and $\phi$ are continuous functions, we can see a constant $D$ independent of $n$ with

$$
\begin{equation*}
\left|v_{i}^{n}(a)-\frac{1}{c} \phi\left(v_{i}^{n}(a), v_{i}^{n}(b)\right)\right| \leq D \tag{3.7}
\end{equation*}
$$

Moreover, by (3.1) and (3.2) we have

$$
\begin{aligned}
\left|v_{i}^{n+1}(t)\right| & =\left|v_{i}^{n}(a)-\frac{1}{c} \phi\left(v_{i}^{n}(a), v_{i}^{n}(b)\right)\right| E_{q, 1}\left(-k_{i}(\psi(t)-\psi(a))^{q}\right) \\
& +\int_{a}^{t} \psi^{\prime}(s)(\psi(t)-\psi(s))^{v-1} E_{q, q}\left(-k_{i}(\psi(t)-\psi(s))\right)^{q} \mid F\left(s, v_{i}^{n}(s)+k_{i} v_{i}^{n}(t) \mid d s\right.
\end{aligned}
$$

Using Lemma 2 along with (3.6) and (3.7), we have

$$
\begin{aligned}
\left|v_{i}^{n+1}(t)\right| & =D+\frac{C}{\Gamma(q)} \int_{a}^{t} \psi^{\prime}(s)(\psi(t)-\psi(s))^{v-1} d s \\
& \leq D+\frac{C(\psi(t)-\psi(s))^{q}}{\Gamma(q+1)}
\end{aligned}
$$

Hence, $v_{i}^{n}$ is uniformly bounded in $C(J, \mathbb{R})$. Similarly $w_{i}^{n}$ is uniformly bounded $C(J, \mathbb{R})$. Next to prove that the sequence $v_{i}^{n}$ and $w_{i}^{n}$ are equi-continuous on $J$. Choosing $t_{1}, t_{2} \in J$, with $t_{1} \leq t_{2}$. By (3.6),(3.7) and

Lemma 2, we have

$$
\begin{aligned}
\left|v_{i}^{n+1}\left(t_{2}\right)-v_{i}^{n+1}\left(t_{1}\right)\right| & \left.\leq\left|v_{i}^{n}(a)-\frac{1}{c} \phi\left(v_{i}^{n}(a), v_{i}^{n}(b)\right)\right| \right\rvert\, E_{q, 1}\left(-k_{i}\left(\psi\left(t_{2}\right)-\psi(a)\right)^{q}\right) \\
& -E_{q, 1}\left(-k_{i}\left(\psi\left(t_{1}\right)-\psi(a)\right)^{q}\right) \mid \\
& \left.\leq \int_{a}^{t_{1}} \frac{\psi^{\prime}(s)\left[\left(\psi\left(t_{1}\right)-\psi(s)\right)^{v-1}-\left(\psi\left(t_{2}\right)-\psi(s)\right)^{v-1}\right]}{\gamma(q)} \right\rvert\, F\left(s, v_{i}^{n}(s)+k_{i} v_{i}^{n}(s) \mid d s\right. \\
& \left.+\int_{t_{1}}^{t_{2}} \frac{\psi^{\prime}(s)\left[\left(\psi\left(t_{2}\right)-\psi(s)\right)^{v-1}\right]}{\Gamma(q)} \right\rvert\, F\left(s, v_{i}^{n}(s)+k_{i} v_{i}^{n}(s) \mid d s\right. \\
& \leq D\left|E_{q, 1}\left(-k_{i}\left(\psi\left(t_{2}\right)-\psi(a)\right)^{q}\right)-E_{q, 1}\left(-k_{i}\left(\psi\left(t_{1}\right)-\psi(a)\right)^{q}\right)\right| \\
& +\frac{2 C\left(\psi\left(t_{2}\right)-\psi\left(t_{1}\right)\right)^{q}}{\Gamma(q+1)}
\end{aligned}
$$

By the continuity of $E_{q, 1}\left(-k_{i}\left(\psi\left(t_{1}\right)-\psi(a)\right)^{q}\right)$ on $J$, the right-hand-side of the preceding inequality approaches zero, when $t_{1} \rightarrow t_{2}$. This implies that $\left\{v_{i}^{n+1}(t)\right\}$ is equi-continuous on $J$. Similarly $\left\{w_{i}^{n+1}(t)\right\}$ is equi-continuous on $J$. Hence, by using Ascoli-Arzelas theorem, the subsequences converges to $v_{i}^{*}(t)$ and $w_{i}^{*}(t)$. Hence the monotonic sequences combined with $v_{i}^{n}(t)$ and $w_{i}^{n}(t)$ yields $\lim _{n \rightarrow \infty} v_{i}^{n}(t)=v_{i}^{*}(t)$ and $\lim _{n \rightarrow \infty} w_{i}^{n}(t)=w_{i}^{*}(t)$, uniformly on $t \in J$ and limit functions $v_{i}^{*}$, $w_{i}^{*}$ satisfy (1.1)

Step 3: $v_{i}^{*}$ and $w_{i}^{*}$ are maximal solutions of (1.1)in $\left[v_{i}^{0}, w_{i}^{0}\right]$ Let $u_{i} \in\left[v_{i}^{0}, w_{i}^{0}\right]$ be any solution of (1.1). Suppose that

$$
\begin{equation*}
v_{i}^{n}(t) \leq u_{i}(t) \leq w_{i}^{n}(t), \quad t \in J \tag{3.8}
\end{equation*}
$$

for some $n \in \mathbb{N}$. To prove that $u_{i}(t) \leq v_{i}^{n}(t)$ Let $\rho_{i}(t)=u_{i}(t)-v_{i}^{n}(t)$. Then from we have

$$
\begin{aligned}
{ }^{c} D_{a^{+}}^{q ; \psi} \rho_{i}(t) & =F_{i}\left(t, u_{i}(t)\right)-F_{i}\left(t, v_{i}^{0}(t)\right)-k_{i}\left(v_{i}^{n+1}(t)-v_{i}^{n}(t)\right) \\
& \geq-k_{i}\left({ }_{i}(t)-v_{i}^{n}(t)\right)+k_{i}\left(v_{i}^{n+1}(t)-v_{i}^{n}(t)\right) \\
& =-k_{i} \rho_{i}(t)
\end{aligned}
$$

Furthermore

$$
\begin{aligned}
v_{i}^{n+1}(a) & =\left(v_{i}^{n}(a)-\frac{1}{c}\left(\phi\left(v_{i}^{n}(a), v_{i}^{n}(b)\right)\right.\right. \\
& =\left(v_{i}^{n}(a)-\frac{1}{c}\left(\phi\left(u_{i}(a), u_{i}(b)\right)-\frac{1}{c}\left(\phi\left(v_{i}^{n}(a), v_{i}^{n}(b)\right)\right.\right.\right. \\
& \leq u_{i}(a)-\frac{d}{c}\left(\left(u_{i}(b)-v_{i}^{n}(b)\right)\right. \\
& \leq u_{i}(a)
\end{aligned}
$$

that is $\rho_{i} \geq 0$. By Lemma 4, we have $\rho_{i} \geq 0, t \in J$ which implies that

$$
v_{i}^{n}(t) \leq u_{i}(t), \quad t \in J
$$

Next we prove that $w_{i}^{n+1}(t) \leq u_{i}(t)$ Let $\rho_{i}(t)=w_{i}^{n+1}(t) \leq u_{i}(t)$. Then from we have

$$
\begin{aligned}
{ }^{c} D_{a+}^{q ; \psi} \rho_{i}(t) & =F_{i}\left(t, w_{i}^{n+1}(t)\right)-F_{i}\left(t, u_{i}(t)\right)-k_{i}\left(u_{i}(t)-u_{i}(t)\right) \\
& \geq-k_{i}\left(w_{i} 6 n(t)-u_{i}(t)\right)+k_{i}\left(u_{i}(t)-u_{i}(t)\right) \\
& =-k_{i} \rho_{i}(t)
\end{aligned}
$$

Furthermore

$$
\begin{aligned}
u_{i}(a) & =\left(u_{i}(a)-\frac{1}{c}\left(\phi\left(u_{i}(a), u_{i}(b)\right)\right.\right. \\
& =\left(u_{i}(a)-\frac{1}{c}\left(\phi\left(w_{i}^{n}(a), w_{i}^{n}(b)\right)-\frac{1}{c}\left(\phi\left(u_{i}(a), u_{i}(b)\right)\right.\right.\right. \\
& \leq w_{i}^{n}(a)-\frac{d}{c}\left(\left(w_{i}^{n}(b)-u_{i}(b)\right)\right. \\
& \leq w_{i}^{n}(a)
\end{aligned}
$$

that is $\rho_{i} \geq 0$. By Lemma 4, we have $\rho_{i} \geq 0, t \in J$ which implies that

$$
u_{i}(t) \leq w_{i}^{n}(t), \quad t \in J
$$

Hence,

$$
v_{i}^{n}(t) \leq u_{i}(t) \leq w_{i}^{n}(t), \quad t \in J
$$

By (4.8) is satisfied on $J$ for all $n \in \mathbb{N}$.For $n \rightarrow \infty$ on (3.8) we have

$$
v_{i}^{*} \leq u_{i} \leq w_{i}^{*}
$$

Hence $v_{i}^{*}, w_{i}^{*}$ are the extremal solutions of (1.1) in $\left[v_{i}^{0}, w_{i}^{0}\right]$
Theorem 3.2 Let all the assumptions of the Theorem 3.1 hold.Further,there exists nonnegative constants $\mathrm{M}, \mathrm{N}$ such that the function $f_{i}$ satisfies the condition

$$
f_{i}\left(x, u_{1}, u_{2}\right)-f_{i}\left(x, v_{1}, v_{2}\right) \leq M\left(u_{1}-v_{1}\right)+N\left(\left(u_{2}-v_{2}\right)\right.
$$

for $v_{i}^{0}(t) \leq u_{i} \leq w_{i}^{0}(t)$. Then the problem $u_{i}(t)$ of (1.1) has a unique solution.
Proof. We know $v_{i}^{0}(t) \leq w_{i}^{0}(t)$ on $J$. It is sufficient to prove that $v_{i}(t)^{0} \geq w_{i}^{0}(t)$ on $J$. Consider $\rho_{i}(t)=$ $w_{i}^{0}(t)-v_{i}^{0}(t)$.Then we have

$$
\begin{aligned}
{ }^{c} D_{a^{+}}^{q ; \psi} \rho_{i}(t) & =F_{i}\left(t, w_{i}^{0}(t)\right)-F_{i}\left(t, v_{i}^{0}(t)\right)-k_{i}\left(w_{i}^{0}(t)-w_{i}^{0}(t)\right)+k_{i}\left(v_{i}^{0}(t)-v_{i}^{0}\right) \\
& \geq-k_{i}\left(w_{i}^{0}(t)-v_{i}^{0}(t)\right)-k_{i}\left(w_{i}^{0}(t)-w_{i}^{0}(t)\right)+k_{i}\left(v_{i}^{0}(t)-v_{i}^{0}(t)\right) \\
& =-k_{i} \rho_{i}(t)
\end{aligned}
$$

Since

$$
\begin{aligned}
\rho(a) & =\left(w_{i}^{0}(a)-v_{i}^{0}(t)\right)-\frac{1}{c}\left(\phi\left(w_{i}^{0}(a), w_{i}^{0}(b)\right)-\phi\left(v_{i}^{0}(a), v_{i}^{0}(b)\right)\right) \\
& \geq \frac{d}{c}\left(\left(w_{i}^{0}(b)-v_{i}^{0}(b)\right.\right. \\
& \geq 0
\end{aligned}
$$

we have $w_{i}^{0}(t) \geq v_{i}^{0}(t), t \in J$. By Lemma 4, we know $p_{i} \geq 0$, implying that $w_{i}^{0}(t) \geq v_{i}^{0}(t)$ on $J$. Hence $v_{i}(t)=u_{i}(t)=w_{i}(t)$

## 4. Conclusion

In this work, initially we have investigate by using monotone iterative method together with upper and lower solutions for boundary value problems involving a generalized system of Caputo derivative of fractional order. The monotone method yields monotone sequences which converges uniformly and monotonically to extremal(maximal and minimal) solutions of (1.1). We have prove that the uniqueness solution of $u_{i}(t)$ of the system.

## Conflict of Interest

The authors have no conflict of interest regarding the publication of this article.

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