



Communications in Nonlinear Analysis



Journal Homepage: www.vonneumann-publishing.com/cna

Best Proximity Point for Prešić Type Mappings on Metric Spaces

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Abstract

In this paper, we define the best proximity point for Prešić type non-self mappings and prove some best proximity point theorems in complete metric spaces. ©2016 All rights reserved.

Keywords: Best proximity point, weak P -property, Prešić type mappings.

2010 MSC: 47H10, 54H25, 90C26.

1. Introduction

There are several generalizations of the Banach contraction principle. One such generalization is given by Prešić [5, 6] in 1965. Ćirić and Prešić [1] generalized the Prešić type mappings in 2007 and proved some fixed point theorems. Now let us assume that A, B be two nonempty subsets of a metric space and $T : A \rightarrow B$. Clearly $T(A) \cap A \neq \emptyset$ is a necessary condition for the existence of a fixed point of T . Now if $T(A) \cap A = \emptyset$, then to find an element $x \in A$ such that $d(x, Tx) = d(A, B)$ which called best proximity point, is the idea of best proximity point theorems. The existence and convergence of best proximity points has generalized by several authors such as Prolla[7], Reich[8], Sadiq Basha[9, 10], Vertivel *et al.*[11] and Omidvari *et al.*[2, 3, 4] in many directions. In this paper we prove some best proximity point theorems for Prešić type non-self mappings in complete metric spaces.

2. Preliminaries

Let A, B be two non-empty subsets of a metric space (X, d) . The following notations will be used throughout this paper:

$$d(y, A) := \inf\{d(x, y) : x \in A\},$$

$$d(A, B) = \inf\{d(x, y) : x \in A \text{ and } y \in B\},$$

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$$A_0 = \{x \in A : d(x, y) = d(A, B) \text{ for some } y \in B\},$$

$$B_0 = \{y \in B : d(x, y) = d(A, B) \text{ for some } x \in A\}.$$

We recall that $x \in A$ is a best proximity point of the non-self mapping $T : A \rightarrow B$ if $d(x, Tx) = \text{dist}(A, B)$. It can be observed that a best proximity reduces to a fixed point, if the underlying mapping is a self-mapping.

Definition 2.1. [12] Let (A, B) be a pair of nonempty subsets of a metric space X with $A \neq \emptyset$. Then the pair (A, B) is said to have the weak P-property, if and only if

$$\left. \begin{array}{l} d(x_1, y_1) = d(A, B), \\ d(x_2, y_2) = d(A, B), \end{array} \right\} \implies d(x_1, x_2) \leq d(y_1, y_2),$$

where $x_1, x_2 \in A_0$ and $y_1, y_2 \in B_0$.

It is clear that, for any nonempty subset A of X , the pair (A, A) has the weak P-property. Prešić[5, 6] introduced a kind of mappings called Prešić type mappings and proved the following theorem.

Theorem 2.2. [5, 6] Let (X, d) be a complete metric space, k a positive integer and $T : X^k \rightarrow X$ a mapping the following contractive type condition:

$$d(T(x_1, x_2, x_3, \dots, x_k), T(x_2, x_3, \dots, x_k, x_{k+1})) \leq \sum_{i=1}^k q_i d(x_i, x_{i+1}), \quad (2.1)$$

for every x_1, \dots, x_{k+1} in X , where q_1, q_2, \dots, q_k are non-negative constants such that $\sum_{i=1}^k q_i < 1$. Then there exists a unique point x in X such that $T(x, x, \dots, x) = x$. Moreover, if x_1, x_2, \dots, x_k are arbitrary points in X and for $n \in \mathbb{N}$,

$$x_{n+k} = T(x_n, x_{n+1}, \dots, x_{n+k-1}),$$

then the sequence $\{x_n\}_{n=1}^{\infty}$ is convergent and

$$\lim x_n = T(\lim x_n, \lim x_n, \dots, \lim x_n).$$

In 2007, Ćirić and Prešić[1] generalized the Prešić type mappings and proved the following theorem.

Theorem 2.3. [1] Let (X, d) be a complete metric space, k a positive integer and $T : X^k \rightarrow X$ a mapping the following contractive type condition:

$$d(T(x_1, x_2, x_3, \dots, x_k), T(x_2, x_3, \dots, x_k, x_{k+1})) \leq \lambda \max\{d(x_i, x_{i+1}) : 1 \leq i \leq k\} \quad (2.2)$$

where $\lambda \in (0, 1)$ is a constant and x_1, \dots, x_{k+1} are arbitrary elements in X . Then there exists a point x in X such that $T(x, x, \dots, x) = x$. Moreover, if x_1, x_2, \dots, x_k are arbitrary points in X and for $n \in \mathbb{N}$,

$$x_{n+k} = T(x_n, x_{n+1}, \dots, x_{n+k-1}),$$

then the sequence $\{x_n\}_{n=1}^{\infty}$ is convergent and

$$\lim x_n = T(\lim x_n, \lim x_n, \dots, \lim x_n).$$

If in addition we suppose that on diagonal $\Delta \subset X^k$,

$$d(T(u, \dots, u), T(v, \dots, v)) < d(u, v), \quad (2.3)$$

holds for all $u, v \in X$, with $u \neq v$, then x is the unique point in X with $T(x, x, \dots, x) = x$.

3. Main Result

We first define a new kind of the best proximity point.

Definition 3.1. Let A and B be two non-empty subsets of a metric space (X, d) . Let k be a positive integer and $T : A^k \rightarrow B$ a non-self mapping. $x \in A$ is said to be a best proximity point of T if,

$$d(x, T(x, \dots, x)) = d(A, B).$$

Theorem 3.2. Let A and B be two non-empty closed subsets of a complete metric space (X, d) such that $A_0 \neq \emptyset$ and (A, B) has the weak P -property. Let k be a positive integer and $T : A^k \rightarrow B$ a non-self mapping satisfies the following condition:

(a) $T(A_0^k) \subseteq B_0$.

(b) There exists $\lambda \in (0, 1)$ such that

$$d(T(x_1, x_2, \dots, x_k), T(x_2, \dots, x_k, x_{k+1})) \leq \lambda \max\{d(x_i, x_{i+1}) : 1 \leq i \leq k\}, \quad (3.1)$$

where x_1, x_2, \dots, x_{k+1} are arbitrary elements in A .

Then T has a best proximity point in A . Moreover, if on diagonal $\Delta \subset A^k$,

$$d(T(u, \dots, u), T(v, \dots, v)) < d(u, v), \quad (3.2)$$

holds for all $u, v \in A$, with $u \neq v$, then T has an unique best proximity point in A .

Proof. Choose $(x_1, x_2, \dots, x_k) \in A_0^k$. Since $T(A_0^k) \subseteq B_0$, there exists $x_{k+1} \in A_0$ such that

$$d(x_{k+1}, T(x_1, x_2, \dots, x_k)) = d(A, B).$$

Again since $(x_2, \dots, x_k, x_{k+1}) \in A_0^k$, there exists $x_{k+2} \in A_0$ such that

$$d(x_{k+2}, T(x_1, \dots, x_k, x_{k+1})) = d(A, B).$$

Continuing this process, we can find a sequence $\{x_n\}$ in A_0 such that

$$d(x_{n+k}, T(x_n, x_{n+1}, \dots, x_{n+k-1})) = d(A, B) \quad \text{for all } n \in \mathbb{N}. \quad (3.3)$$

We will prove the convergence of sequence $\{x_n\}$ in A . (A, B) satisfies the weak P -property, therefore from (3.3) we obtain for all $n \in \mathbb{N}$,

$$d(x_{n+k}, x_{n+k+1}) \leq d(T(x_n, x_{n+1}, \dots, x_{n+k-1}), T(x_{n+1}, \dots, x_{n+k-1}, x_{n+k})). \quad (3.4)$$

Put $\alpha_n = d(x_n, x_{n+1})$. We will prove by induction the following inequality;

$$\alpha_n \leq K\theta^n \quad \text{for all } n \in \mathbb{N}, \quad (3.5)$$

where $\theta = \lambda^{\frac{1}{k}}$ and $K = \max\{\frac{\alpha_1}{\theta}, \frac{\alpha_2}{\theta^2}, \dots, \frac{\alpha_k}{\theta^k}\}$.

Obviously, $0 \leq \theta < 1$ and (3.5) is true for $n = 1, \dots, k$. Now let

$$\alpha_n \leq K\theta^n, \alpha_{n+1} \leq K\theta^{n+1}, \dots, \alpha_{n+k-1} \leq K\theta^{n+k-1},$$

be the induction hypotheses. Then by the definition of T and the induction hypotheses and using (3.4), we have

$$\begin{aligned}
 \alpha_{n+k} &= d(x_{n+k}, x_{n+k+1}) \\
 &\leq d(T(x_n, x_{n+1}, \dots, x_{n+k-1}), T(x_{n+1}, \dots, x_{n+k-1}, x_{n+k})) \\
 &\leq \lambda \max\{\alpha_i : i = n, \dots, n+k-1\} \\
 &\leq \lambda \max\{K\theta^i : i = n, \dots, n+k-1\} \\
 &= \lambda K\theta^n = K\theta^{n+k},
 \end{aligned} \tag{3.6}$$

and this complete the inductive proof. Now let $m, n \in \mathbb{N}$ such that $m \geq n$. By using (3.5), we receive that

$$\begin{aligned}
 d(x_n, x_m) &\leq \sum_{i=n}^{m-1} d(x_i, x_{i+1}) \\
 &\leq \sum_{i=n}^{m-1} K\theta^i \\
 &\leq K\theta^n \sum_{i=1}^{\infty} \theta^i \\
 &= \frac{K\theta^n}{1-\theta}.
 \end{aligned}$$

Therefore $\{x_n\}$ is a Cauchy sequence in A . Since X is a complete metric space and A is a closed subset of X , there exists $x \in A$ such that $\lim_{n \rightarrow \infty} x_n = x$. Then for any $n \in \mathbb{N}$, we have

$$\begin{aligned}
 d(x, T(x, \dots, x)) &\leq d(x, x_{n+k}) + d(x_{n+k}, T(x_n, x_{n+1}, \dots, x_{n+k-1})) + d(T(x_n, x_{n+1}, \dots, x_{n+k-1}), T(x, \dots, x)) \\
 &\leq d(x, x_{n+k}) + d(A, B) + d(T(x, \dots, x, x), T(x, \dots, x, x_n)) \\
 &\quad + d(T(x, \dots, x, x_n), T(x, \dots, x_n, x_{n+1})) + \dots \\
 &\quad + d(T(x, x_n, x_{n+1}, \dots, x_{n+k-2}), T(x_n, x_{n+1}, \dots, x_{n+k-1})) \\
 &\leq d(x, x_{n+k}) + d(A, B) + \lambda d(x, x_n) \\
 &\quad + \lambda \max\{d(x, x_n), d(x_n, x_{n+1})\} + \dots + \lambda \max\{d(x, x_n), d(x_n, x_{n+1}), \dots, d(x_{n+k-2}, x_{n+k-1})\}.
 \end{aligned}$$

Letting $n \rightarrow \infty$ in the above inequality, we obtain that $d(x, T(x, \dots, x)) = d(A, B)$. Also, we received that

$$d(\lim x_n, T(\lim x_n, \dots, \lim x_n)) = d(A, B).$$

Now suppose (3.2) holds. we show that x is unique. Let $x^* \in A$ be a best proximity point of T such that $x \neq x^*$. Since (A, B) has the weak P -property and (3.2) holds,

$$d(x, x^*) \leq d(T(x, \dots, x), T(x^*, \dots, x^*)) < d(x, x^*),$$

which is a contradiction. Hence x is an unique element in A and this completes the proof of theorem. \square

Remark 3.3. Theorem 3.2 is a generalization of Theorem 2.3 if $A = B = X$.

The following result is an immediate consequence of Theorem 3.2.

Corollary 3.4. *Let A and B be two non-empty closed subsets of a complete metric space (X, d) such that $A_0 \neq \emptyset$ and (A, B) has the weak P -property. Let k be a positive integer and $T : A^k \rightarrow B$ a non-self mapping satisfies the following condition:*

$$(a) \quad T(A_0^k) \subseteq B_0.$$

(b) There exist non-negative constants q_1, q_2, \dots, q_k such that $\sum_{i=1}^k q_i < 1$ and

$$d(T(x_1, x_2, x_3, \dots, x_k), T(x_2, x_3, \dots, x_k, x_{k+1})) \leq \sum_{i=1}^k q_i d(x_i, x_{i+1}),$$

where x_1, x_2, \dots, x_{k+1} are arbitrary elements in A .

Then T has a best proximity point in A . Moreover, if on diagonal $\Delta \subset A^k$,

$$d(T(u, \dots, u), T(v, \dots, v)) < d(u, v),$$

holds for all $u, v \in A$, with $u \neq v$, then T has an unique best proximity point in A .

Proof. Put $\lambda = \sum_{i=1}^k q_i$. Obviously T satisfies in (3.1) and this completes the proof of corollary. \square

Example 3.5. Let $X = \mathbb{R}$ with the usual metric. Given $A = \{-2, 2\}$, $B = \{-1, 1\}$ and $T : A^2 \rightarrow B$ by

$$T(x, y) = \begin{cases} \frac{x+y}{4}, & x = y, \\ \frac{x+y}{4} + 1, & x \neq y, \end{cases}$$

It is clear that, for any $\lambda \in (\frac{1}{2}, 1)$, the non-self mapping T satisfies in the conditions of Theorem 3.2 and $d(-2, T(-2, -2)) = d(2, T(2, 2)) = d(A, B)$.

4. Acknowledgement

The author would like to thanks to Islamic Azad University, Abarkouh Branch, to support this research.

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